



Computational Assessment of Eddy Currents in Rotating Machines


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for electrical engineering



Disclaimers


The materials for this presentation were developed by the application teams of the Groupe Cedrat, at Cedrat SA and Magsoft Corporation.

The topologies used for the examples are drawn from real devices, they are only representative of the real devices.



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Introduction

Evaluation of eddy currents in:

- permanent magnets - radial field machines,
- airgap sleeves on rotor – radial field machines,
- coil conductors – axial field machines.

Why? Eddy currents may:


- alter the torque,
- affect the efficiency,
- generate heat.

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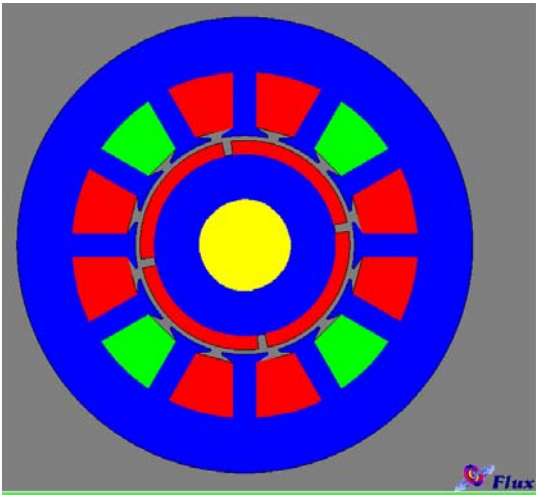
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Permanent Magnet - Radial

4 poles
12 slots
1 mm airgap
23 mm rotor radius
radial surface magnet
NDFE30
 $B_r = 1.21$
 $\mu = 1.0446$
 $\rho = 1.6e-5 \text{ Ohm.m}$

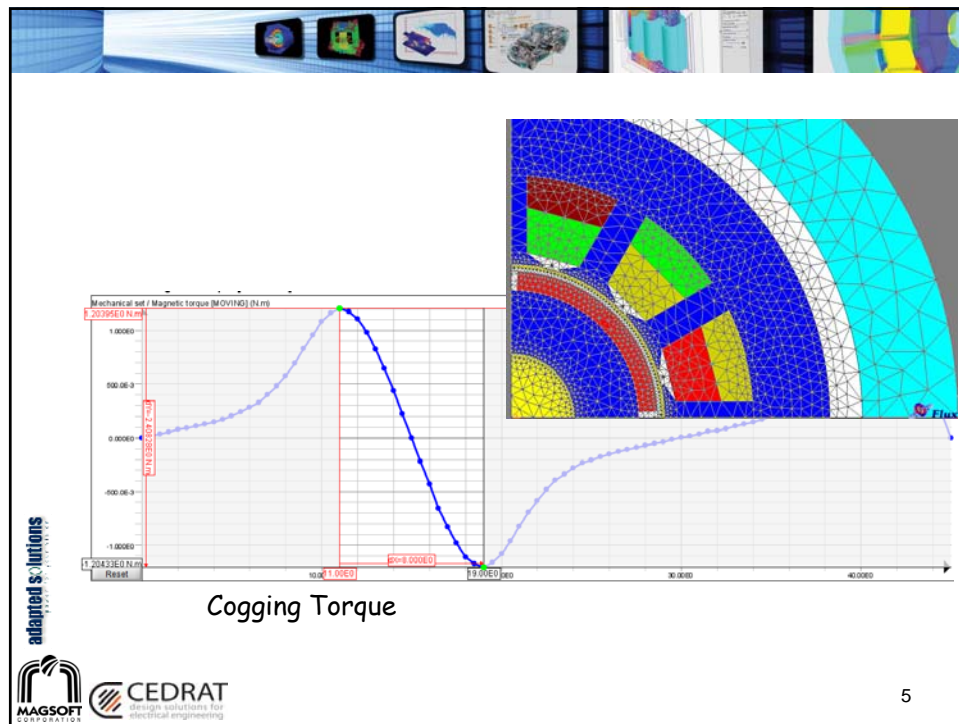


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Eddy currents from motion only

The magnet is conductor, and set in open circuit
the currents must close back inside the magnet,
total current in magnet is none.

The rotor is set in motion

no current input – only effect of slotting

5 speeds:

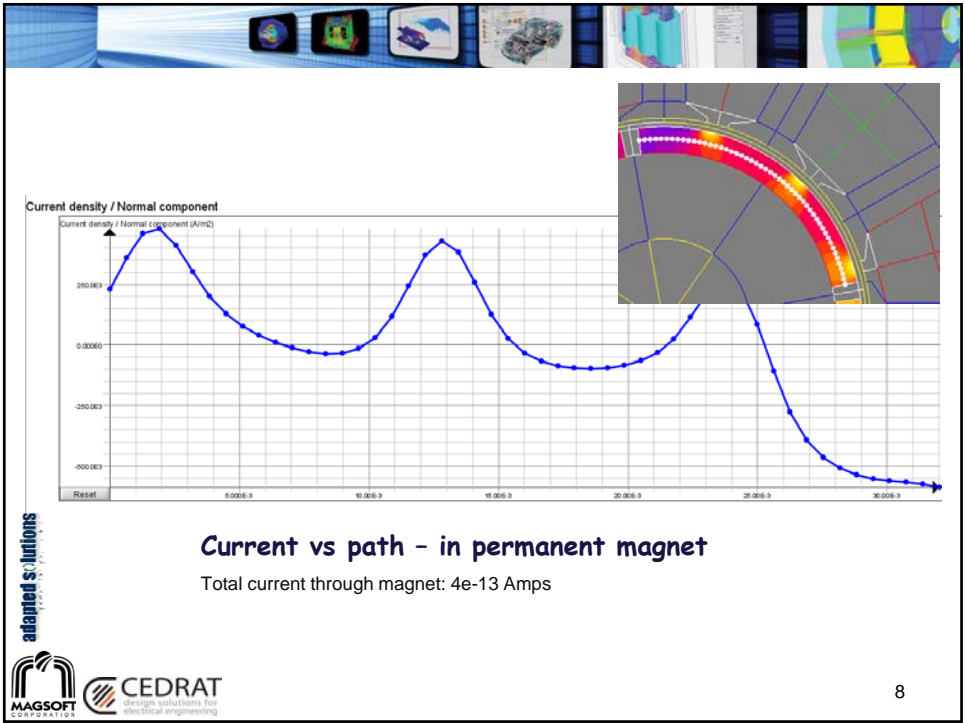
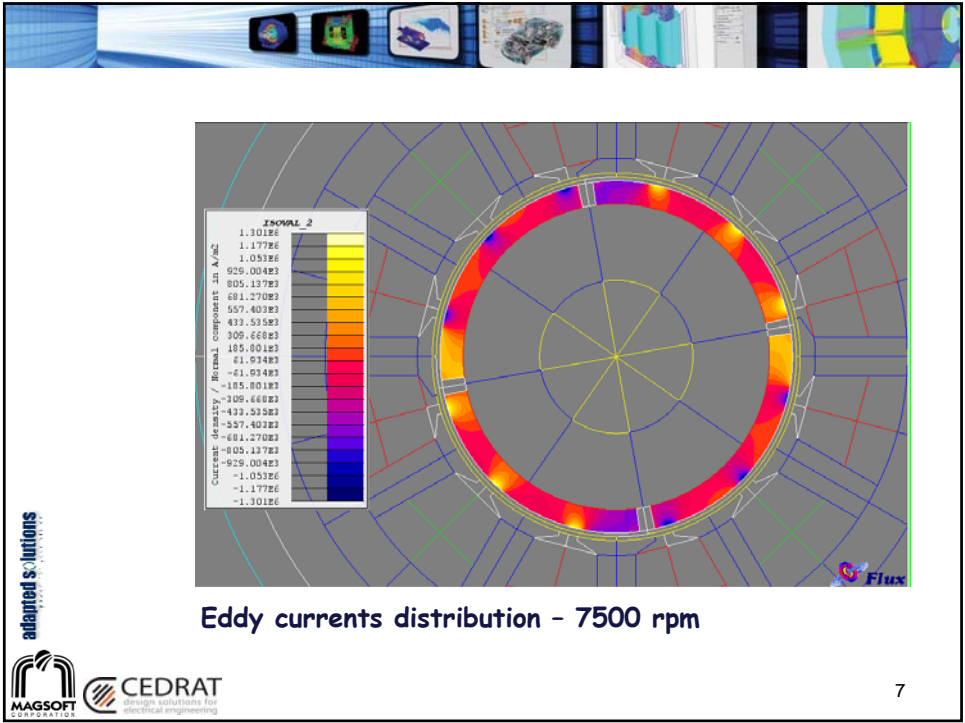
500

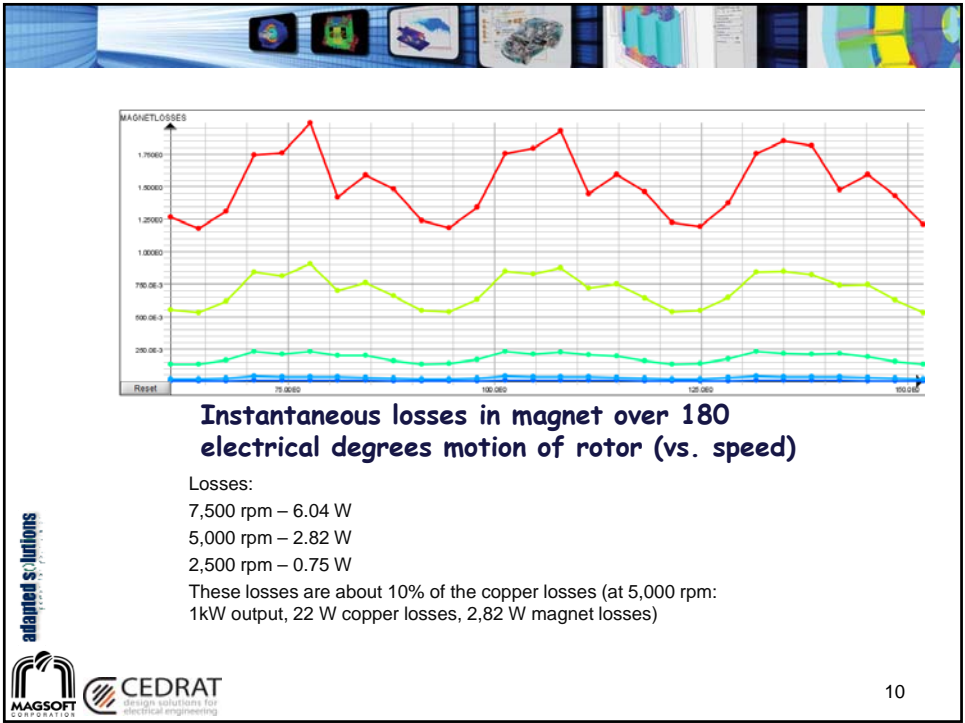
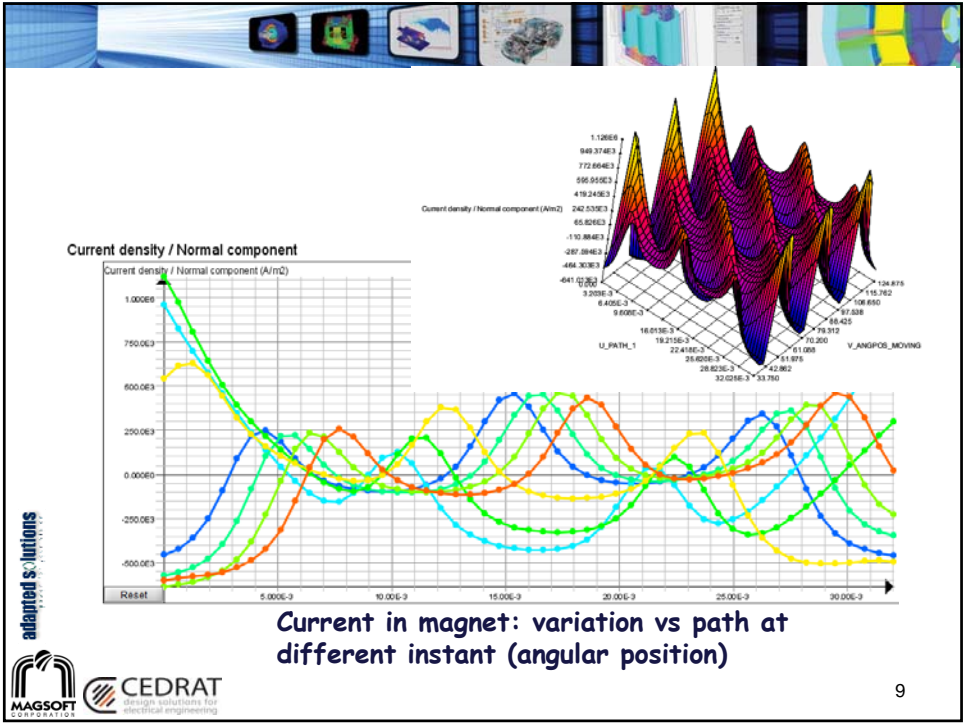
1000


2500

5000

7500

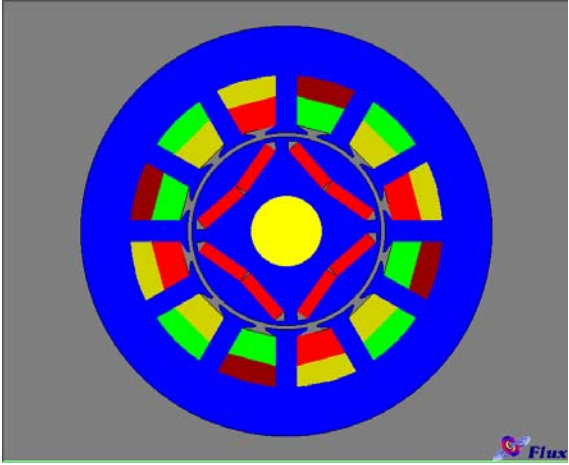









Permanent Magnet (IPM)- Radial

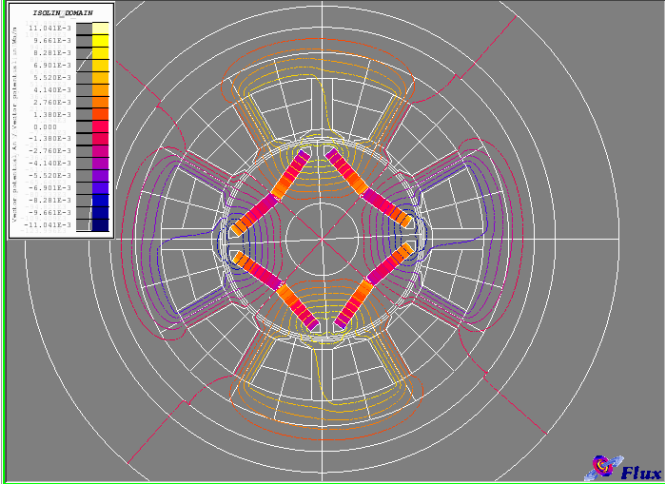
4 poles
12 slots
1 mm airgap
23 mm rotor radius
radial surface magnet
NDFE30
 $B_r = 1.21$
 $\mu_r = 1.0446$
 $\rho = 1.6e-5 \text{ Ohm.m}$







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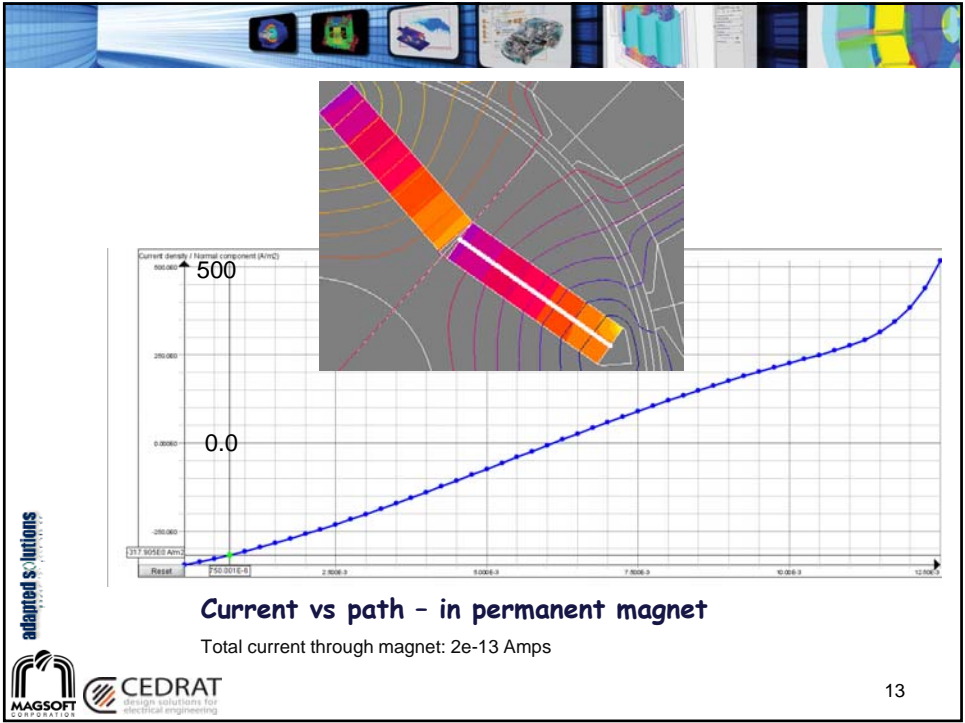




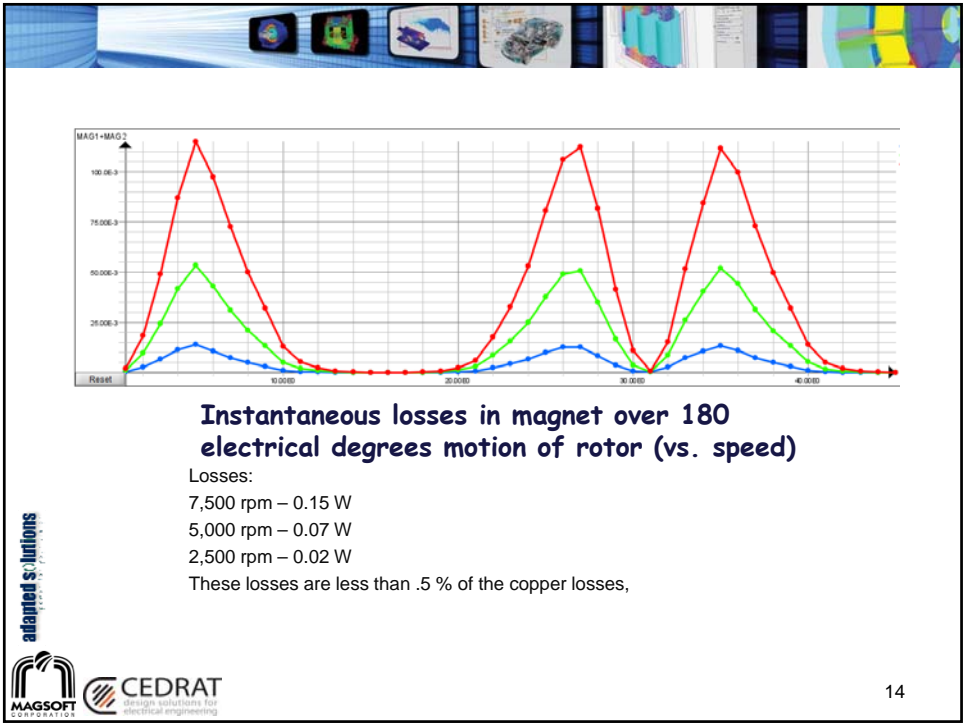
Eddy currents distribution and flux lines - 7500 rpm




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Eddy currents from motion and pwm current



The magnet is conductor, and set in open circuit:

- the currents must close back inside the magnet,
- total current in magnet is none.


The rotor is set in motion:

- coils are current fed,
- currents are the one generated by the power supply,
- speed is 8,000 rpm.

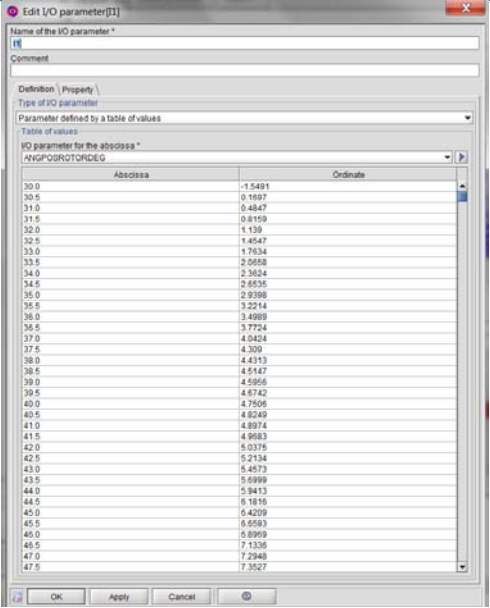
The topology used is the surface magnet.
Same materials.





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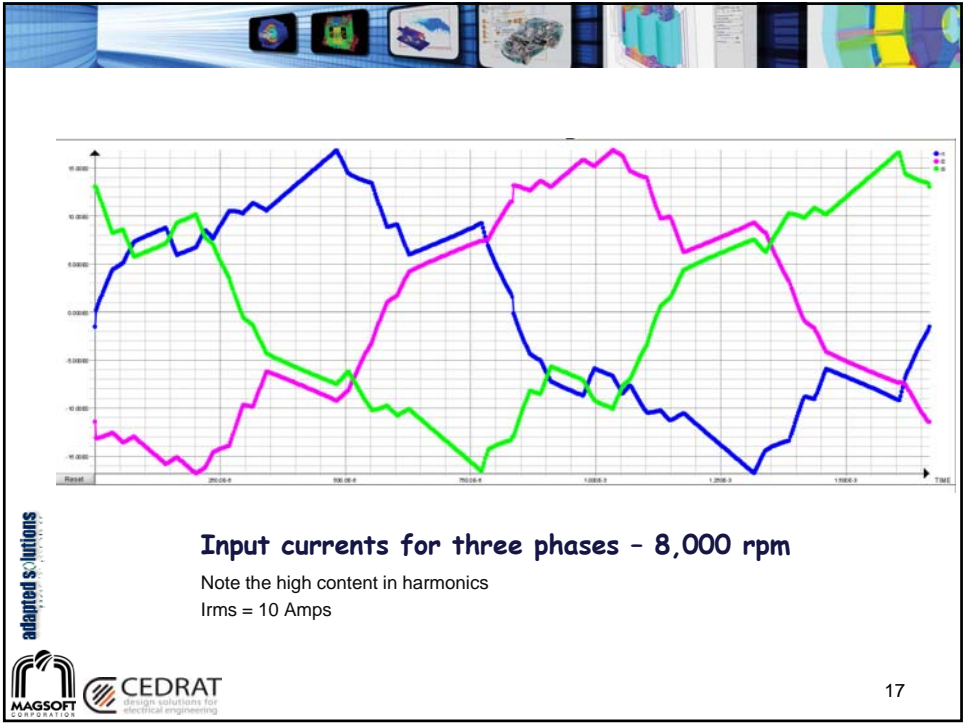
current table
current vs. angle
(mechanical angle)
imported from
text file



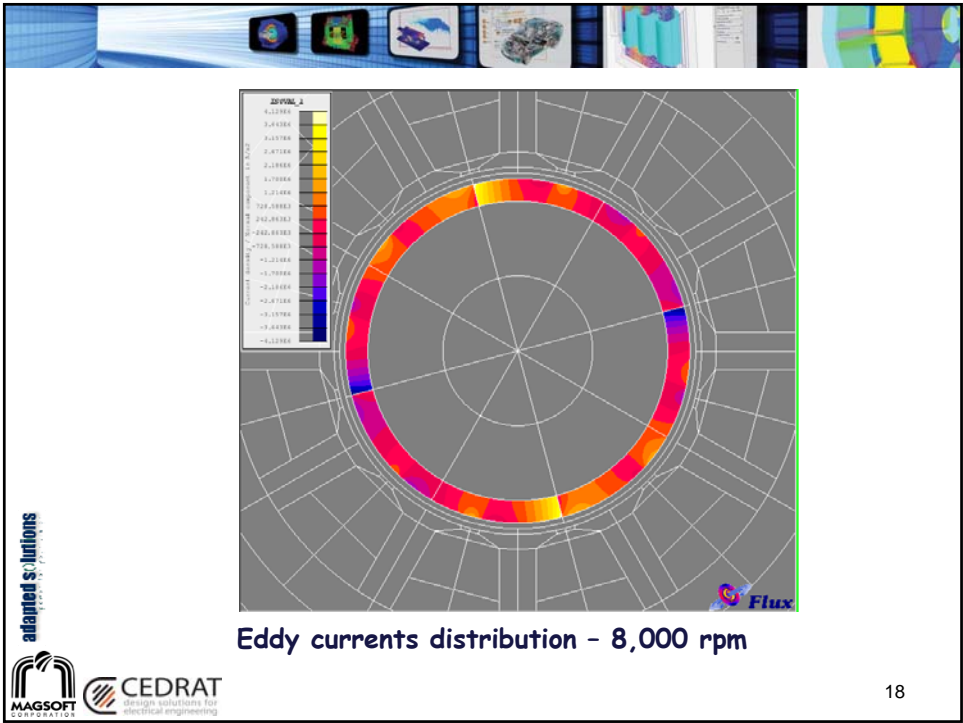
Abcissa	Ordinate
30.0	-1.5491
30.5	0.1697
31.0	0.4847
31.5	0.8159
32.0	1.139
32.5	1.4547
33.0	1.7634
33.5	2.0659
34.0	2.3624
34.5	2.6535
35.0	2.9398
35.5	3.2214
36.0	3.4989
36.5	3.7724
37.0	4.0424
37.5	4.309
38.0	4.4313
38.5	4.5147
39.0	4.5566
39.5	4.6742
40.0	4.7506
40.5	4.8249
41.0	4.8974
41.5	4.9683
42.0	5.0376
42.5	5.1144
43.0	5.1873
43.5	5.2599
44.0	5.3413
44.5	5.4186
45.0	5.4209
45.5	5.4583
46.0	5.8969
46.5	7.1336
47.0	7.2448
47.5	7.3527



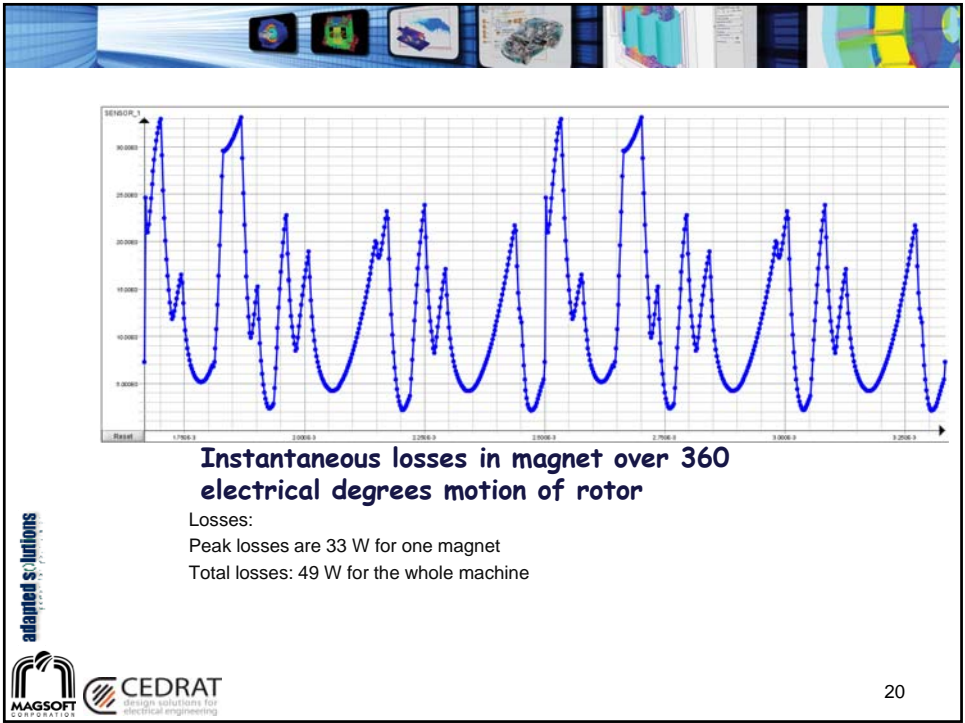
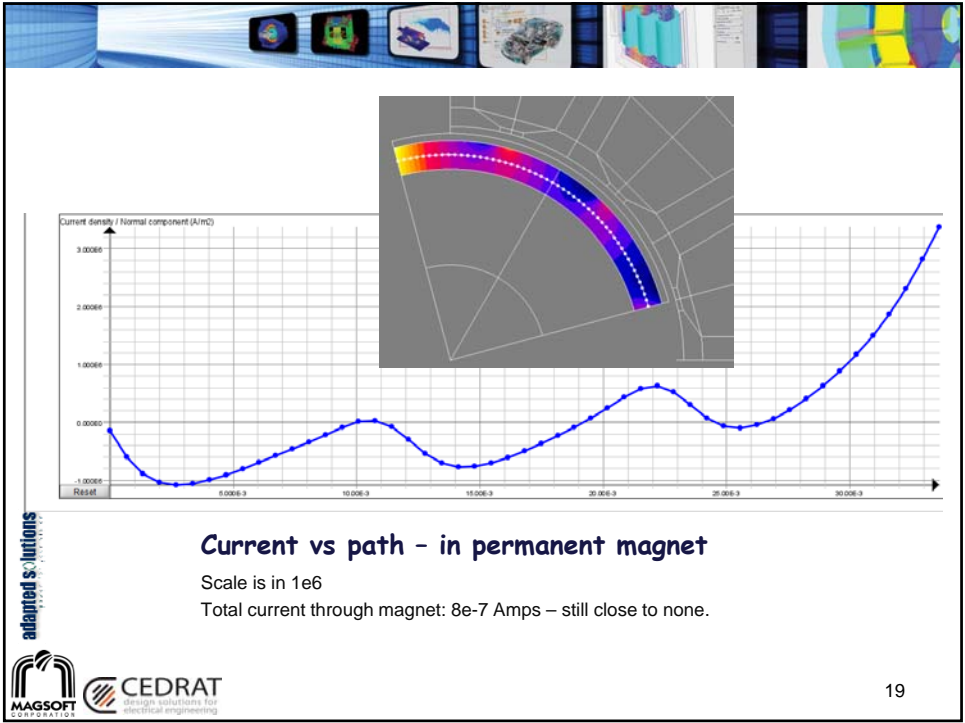
16



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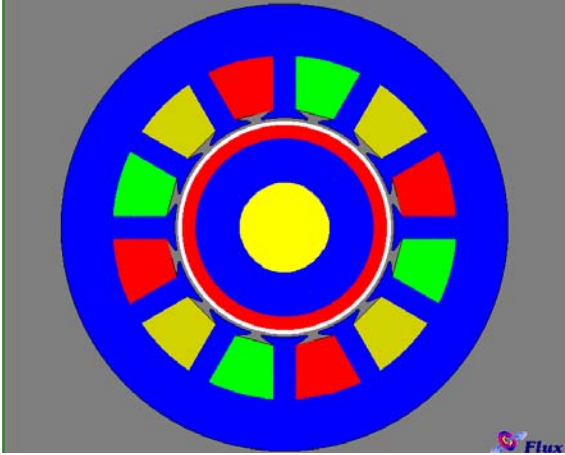




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Airgap Sleeves on Rotor/Magnets

4 poles
12 slots
1.5 mm airgap
.75 mm can
 $\text{Rho} = 2.93\text{e-}8 \text{ Ohm.m}$
23 mm rotor radius
radial surface magnet
Ferrite
 $\text{Br} = 0.4$
 $\text{Mu} = 1.0$








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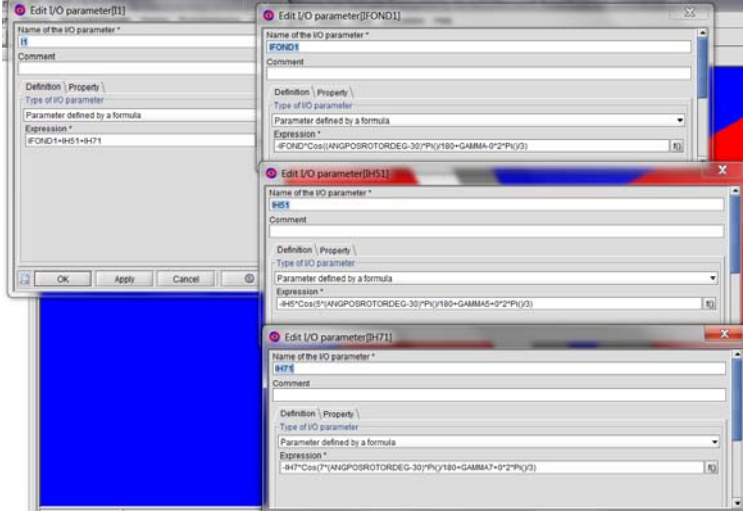
Eddy currents from motion and multi harmonic current

The sleeve is conductor, and set in open circuit
the currents must close back inside the sleeve,
total current in the sleeve is none.



The rotor is set in motion
speed is 18,000 rpm
coils are current fed
fundamental, 5th and 7th harmonics are included

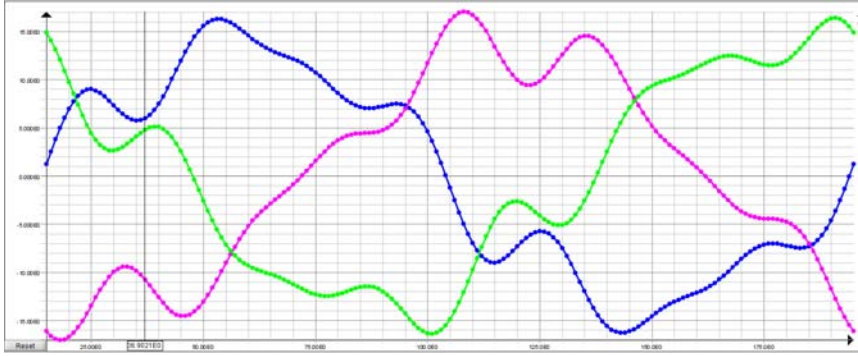



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Current description





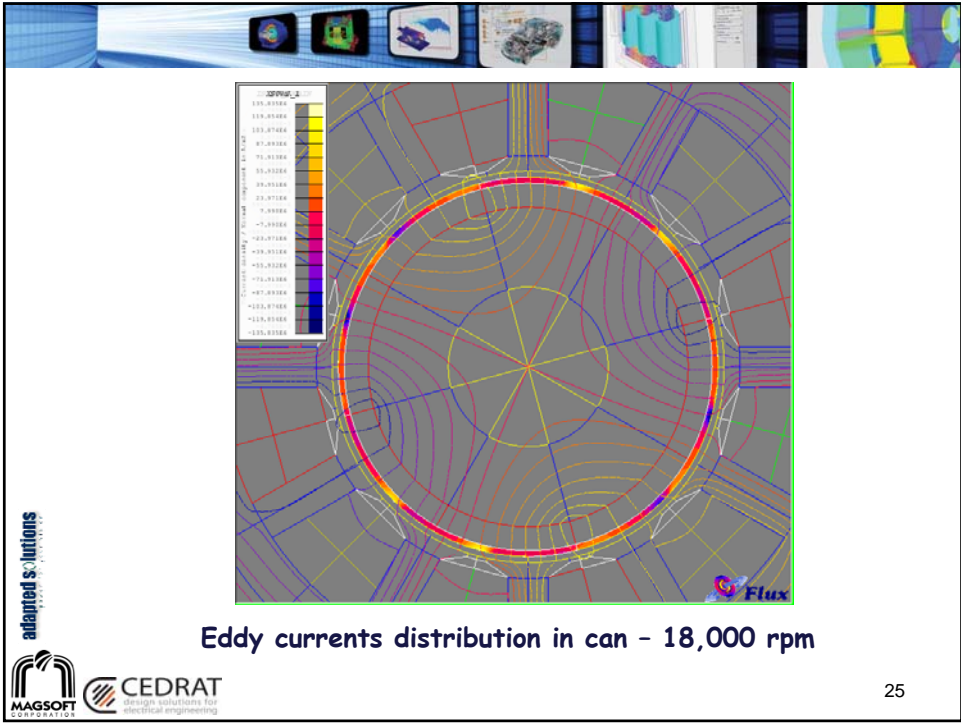


Input currents for three phases - 18,000 rpm

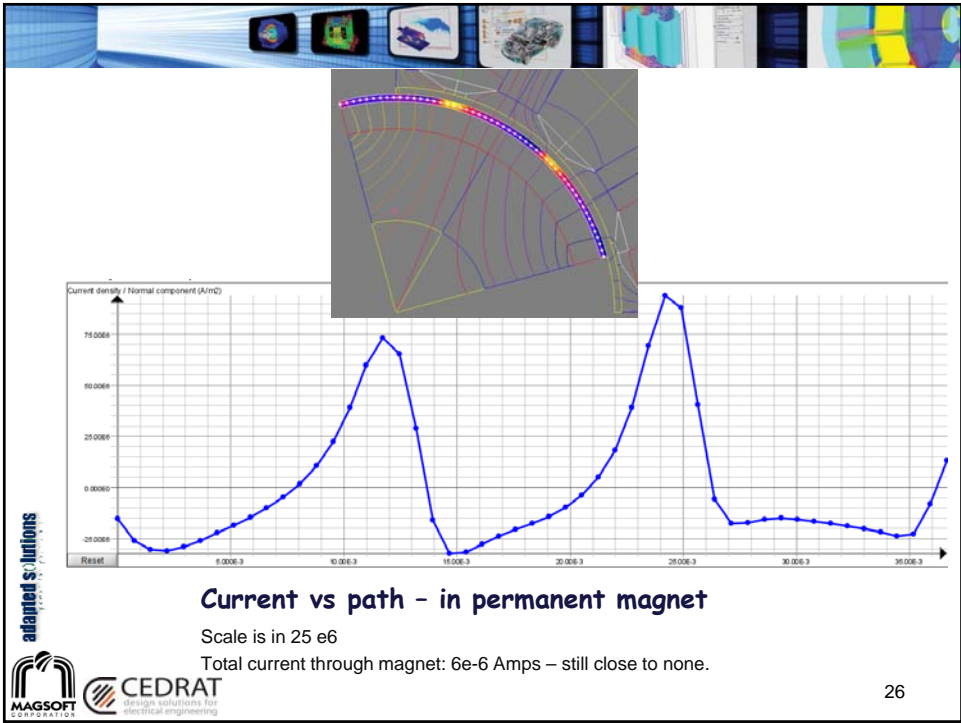
Note the content in harmonics

Irms = 10 Amps

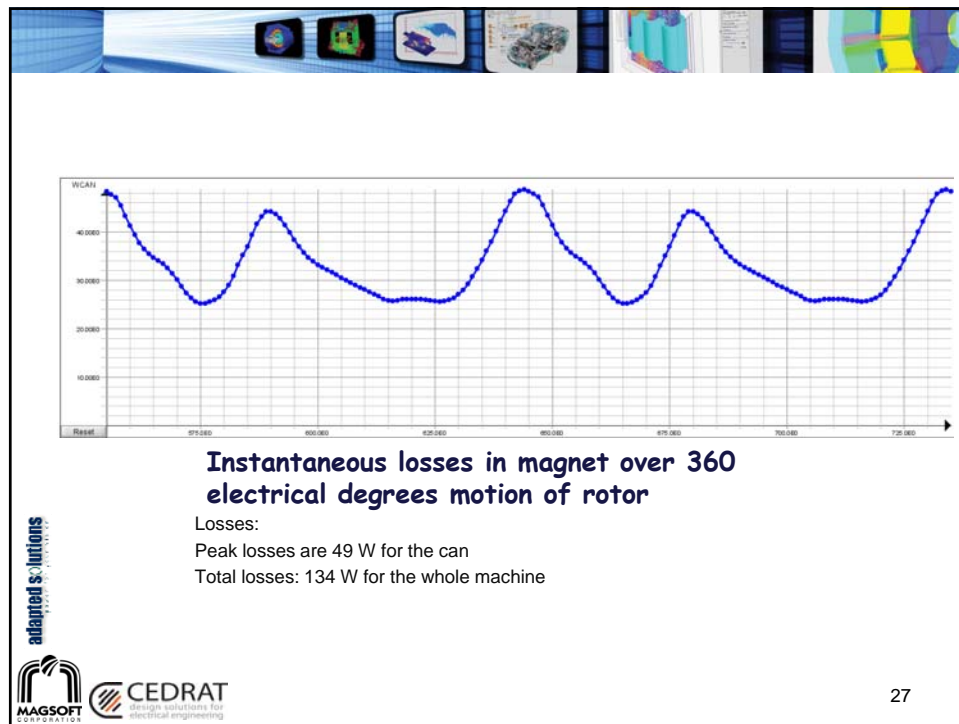




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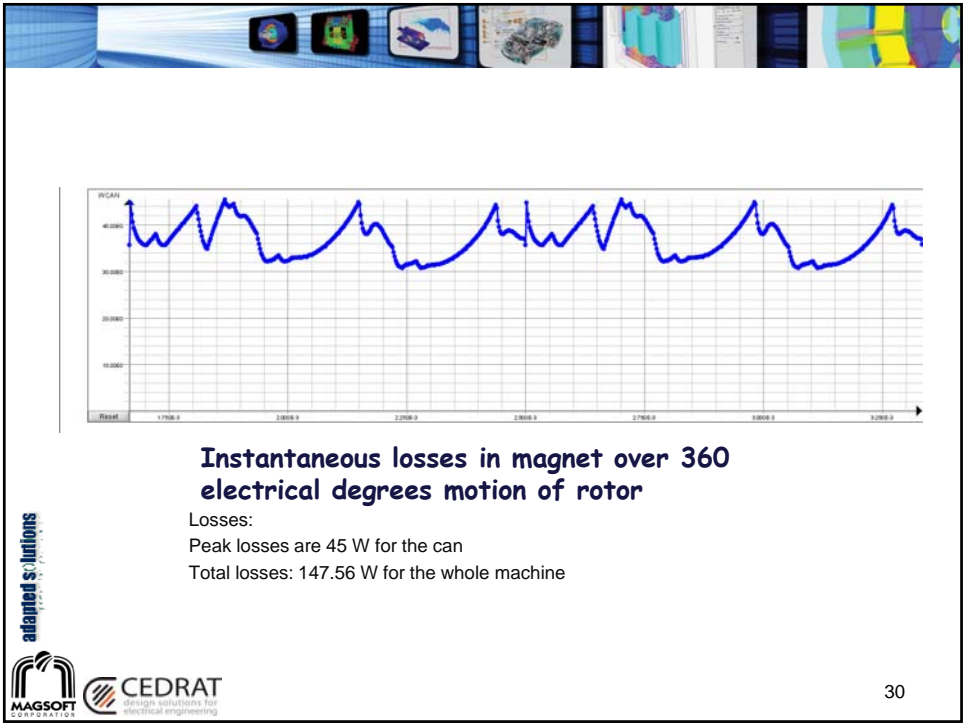
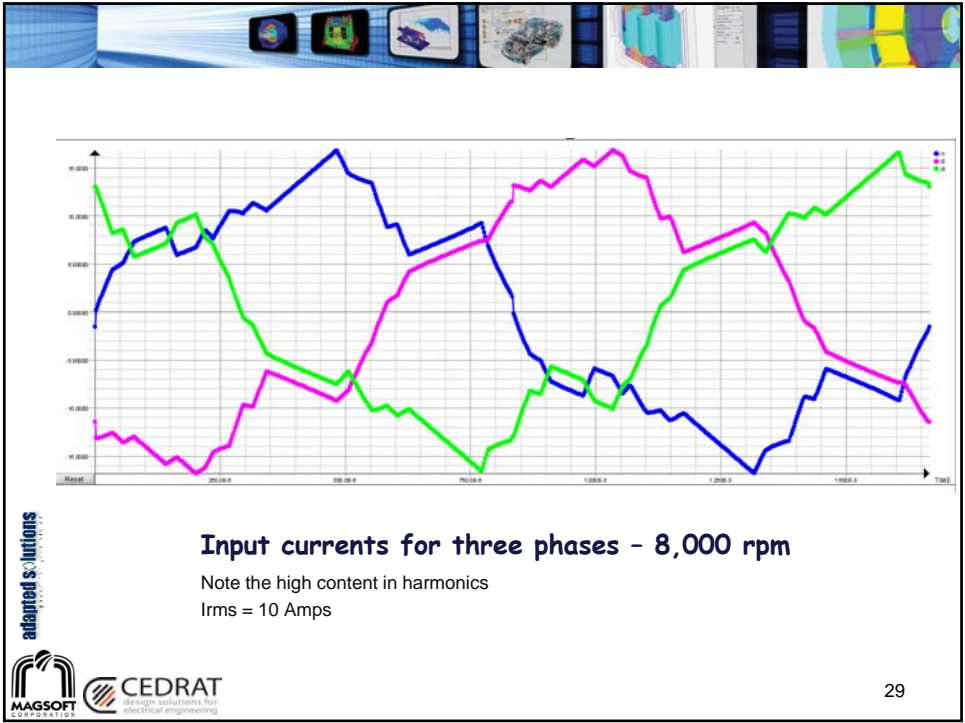
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Eddy currents from motion and pwm current

The sleeve is conductor, and set in open circuit
 the currents must close back inside the sleeve,
 total current in the sleeve is none.

The rotor is set in motion
 speed is 18,000 rpm
 coils are current fed
 currents are the one generated by the power supply

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Computer Time

The losses is slightly higher than when trying to approximate the current with a formula containing the lower harmonics only (134 W)


721 time samples are needed to capture the harmonics when the current is described by a formula. 25 minutes on a i7 processor

1441 time samples are needed to capture the harmonics when the current is described by the tables 40 minutes on a i7 processor

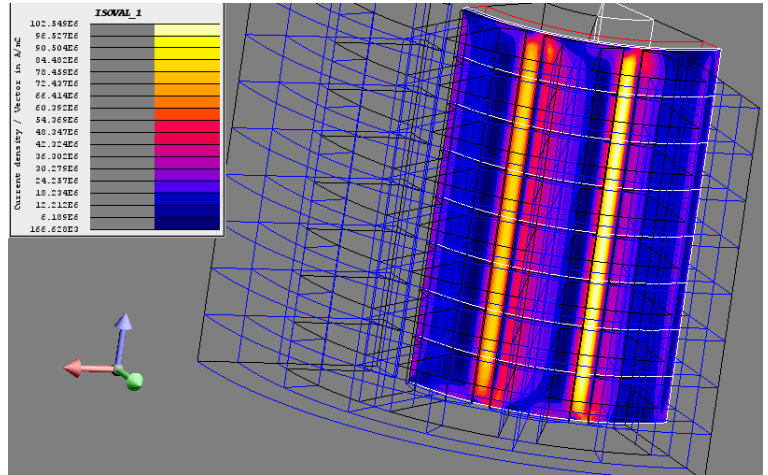

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What About 3D




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The same problem is being treated in 3D
The losses are confirmed at 125.08 W.
The lower number can be explained by the fact that in 2D
we are underestimating the resistance in the 3rd
dimension
361 time samples were computed in 24 hours on a 64 bit
i7 PC with 8GB of RAM

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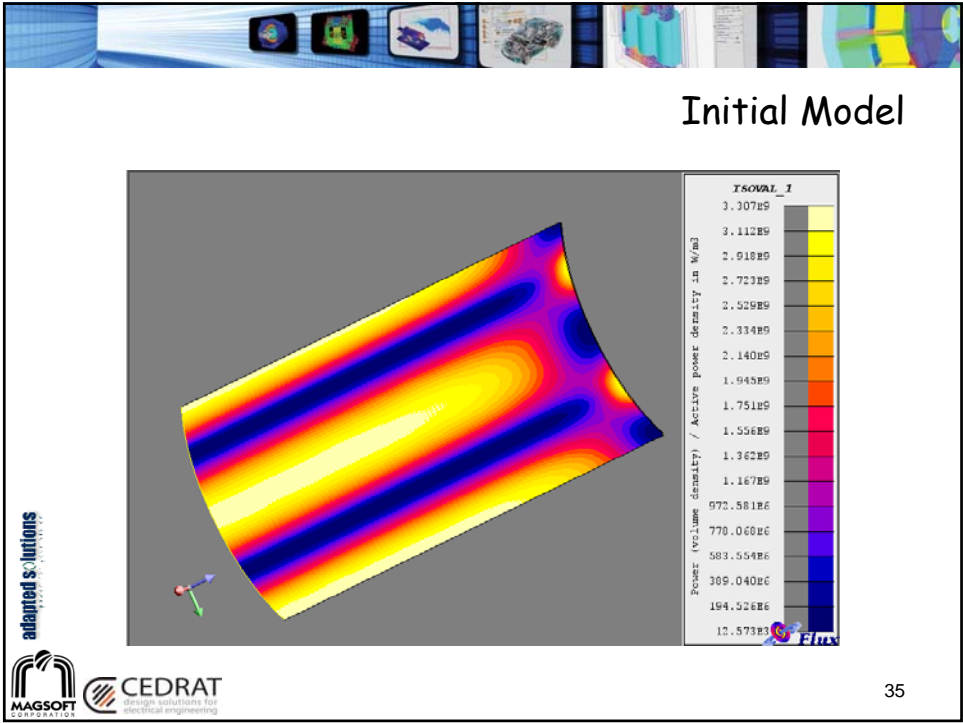
Other Machine

Minimization of losses in a PM machine
PM machine, 8 Poles – Coupler
High speed application
Inconel liner in airgap.
radius 146 mm, 2 mm thick

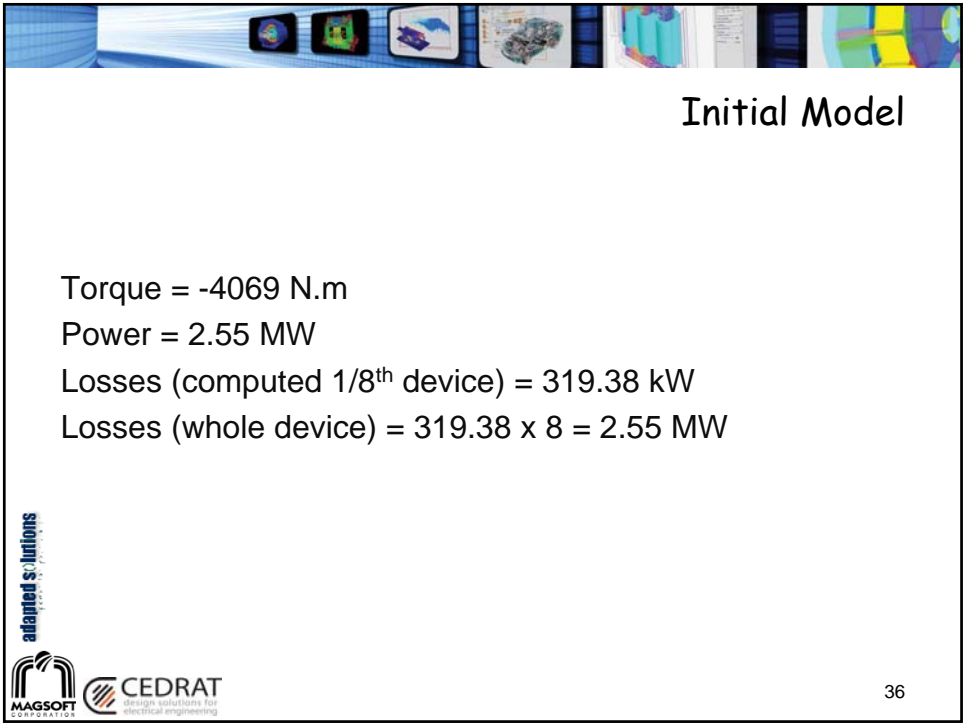
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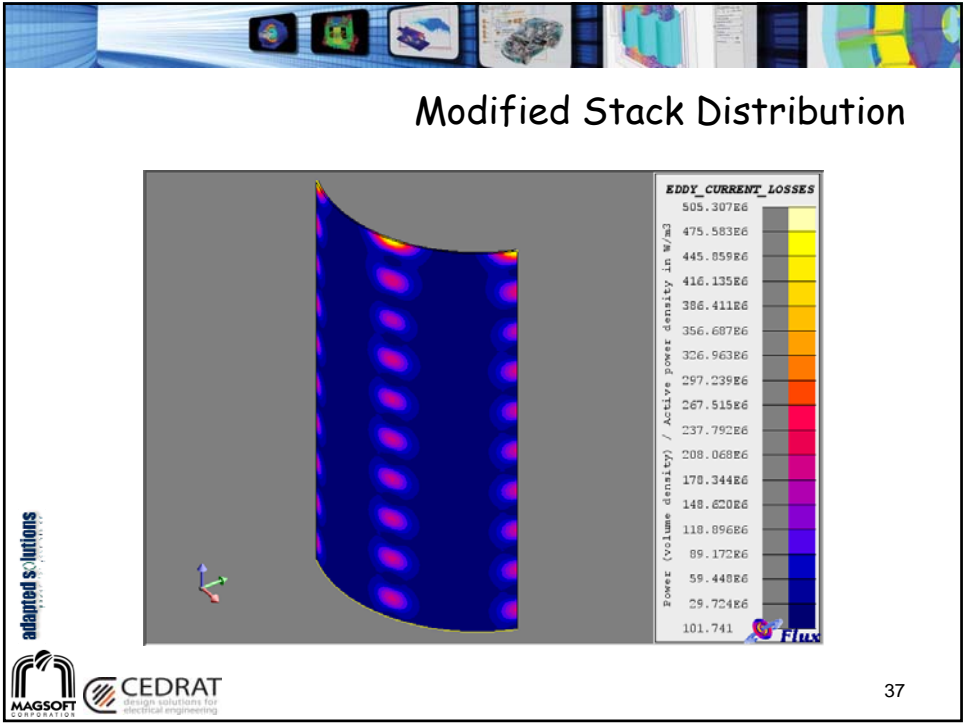
34



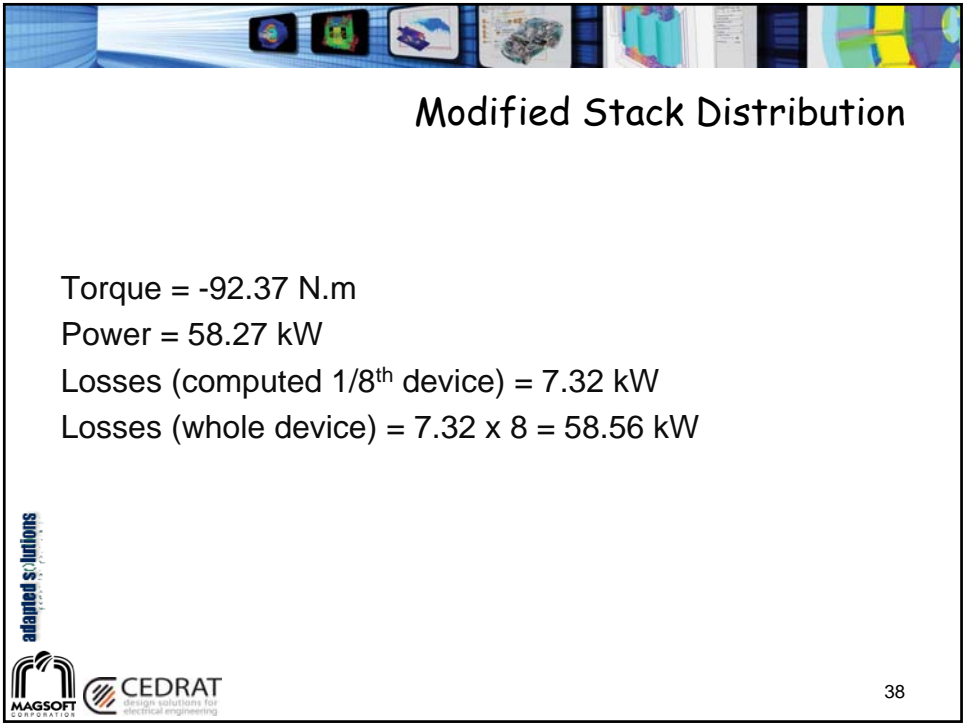
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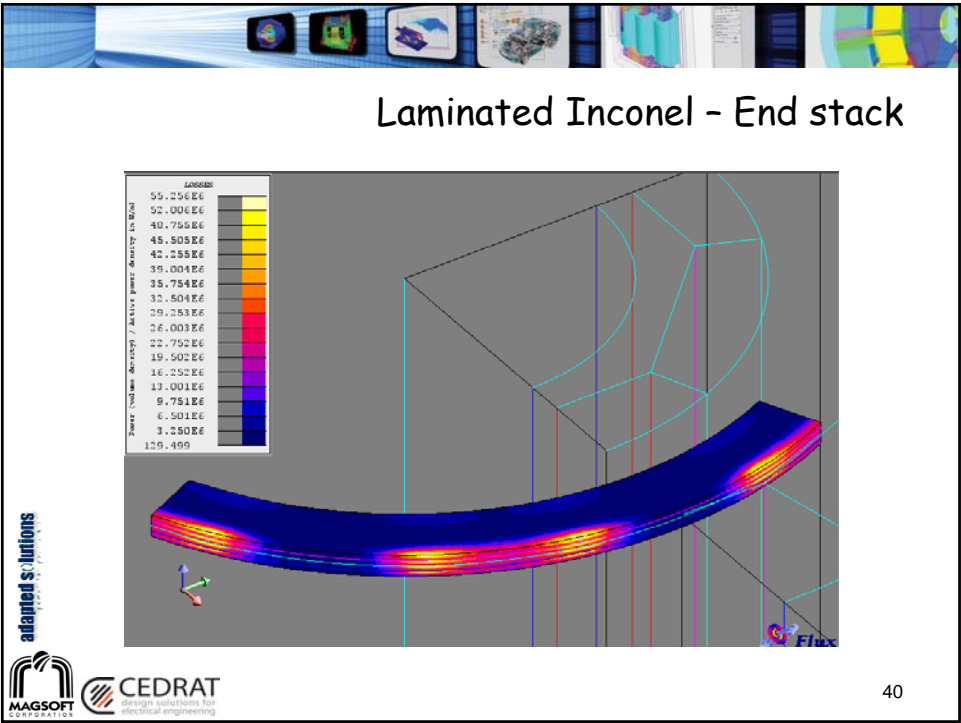
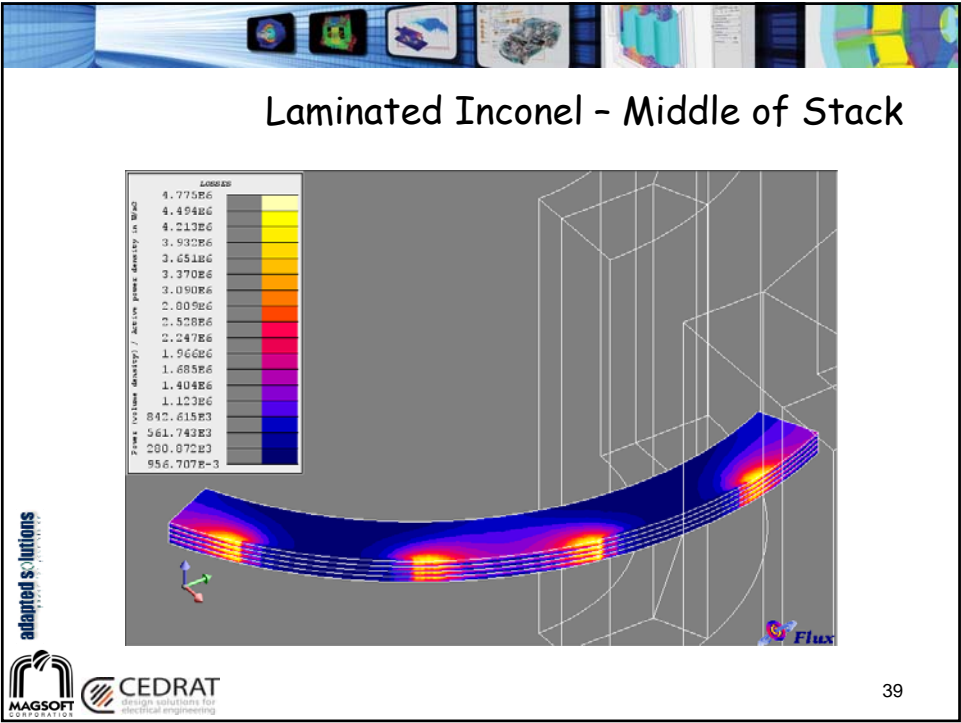
36

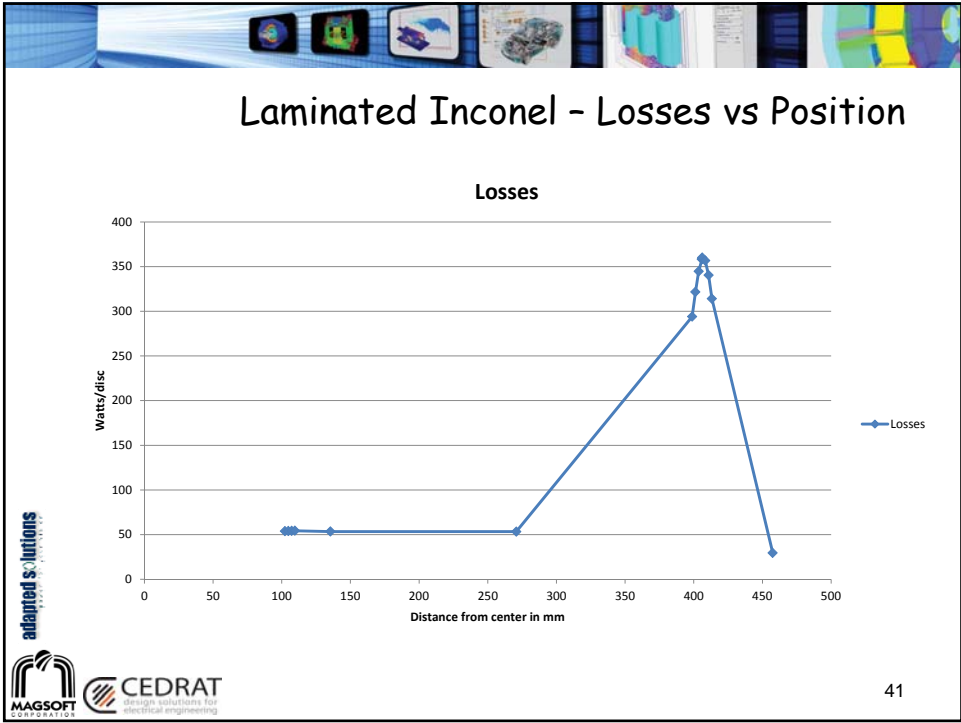


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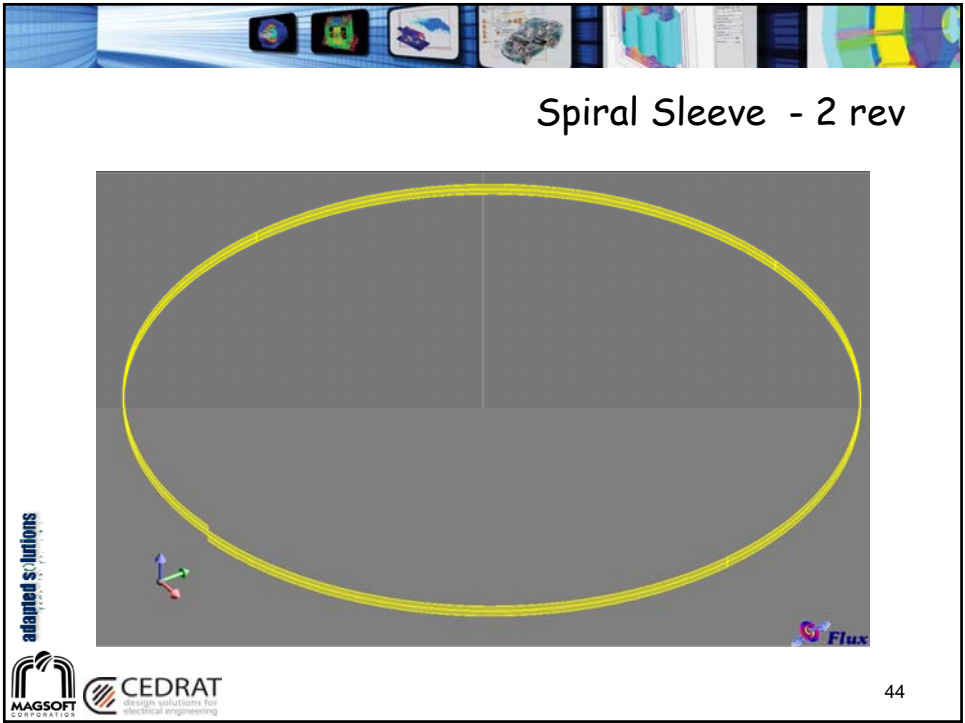
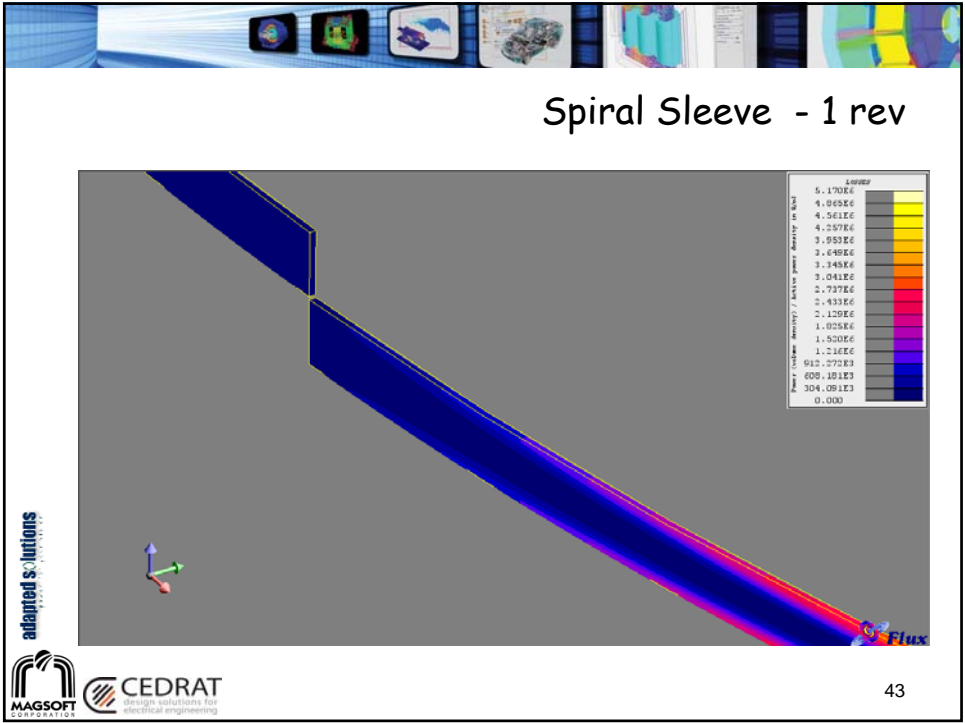


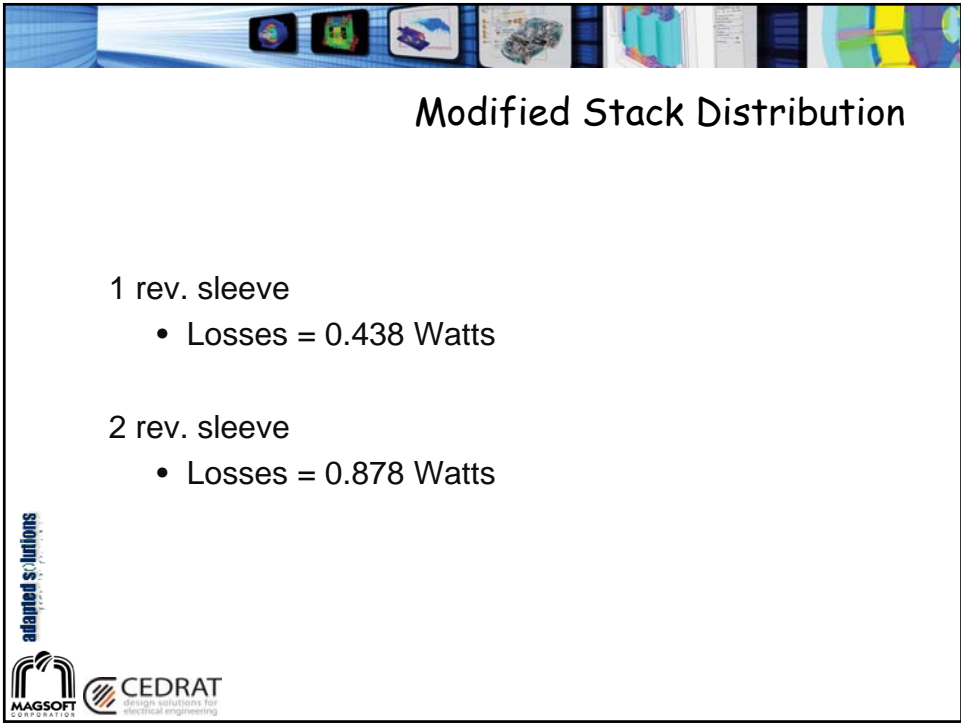
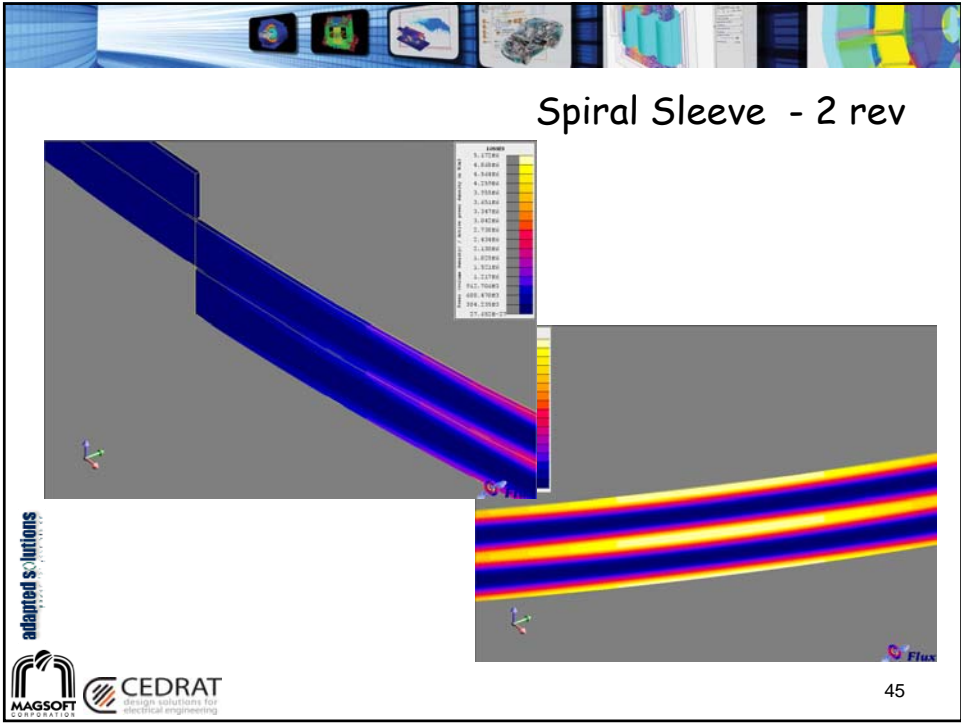
Laminated Inconel - Losses vs Position

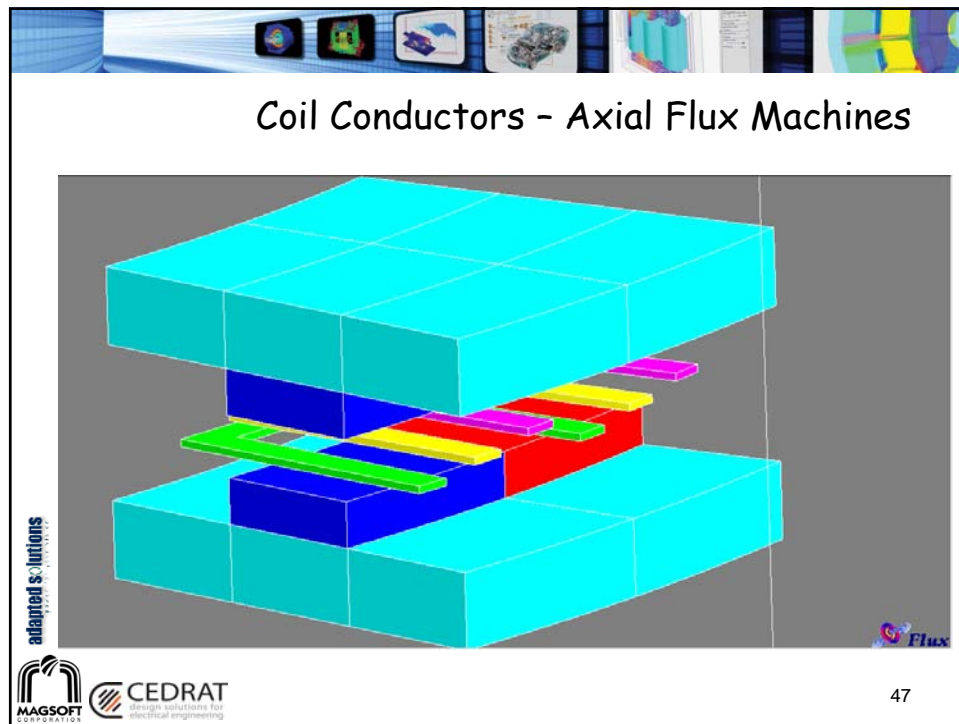
mm	Watts		
Z	Losses		
102.4	53.92	4 layers inside	
104.8	54.04		
107.2	54.2		
109.6	54.36		
135.4	53.424	4 discs	
270.8	53.336		
406.2	360.12		
457.5	29.556		
398.8	293.928	4 layers edge 1	
401.2	321.536		
403.6	344.768		
406	358.28		
406	358.32	4 layers edge 2	
408.4	356.68		
410.8	340.36		
413.2	314		

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Topology

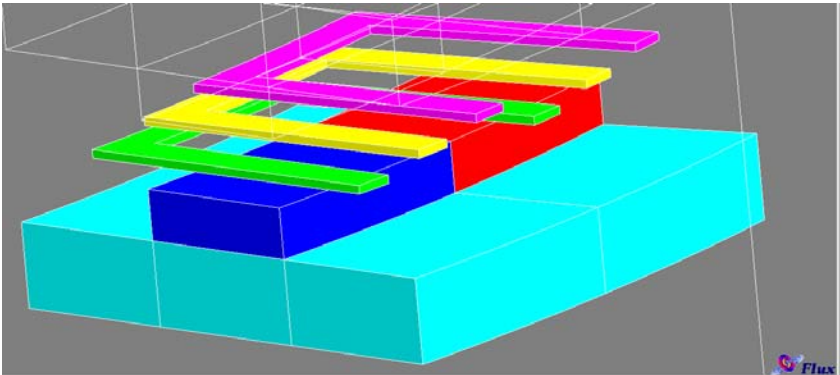
- Two rotors
- Airgap winding
- 3 phases
- 60 poles
- Average radius 140 mm
- NDFE30 magnets
- Copper coils

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Detail Winding



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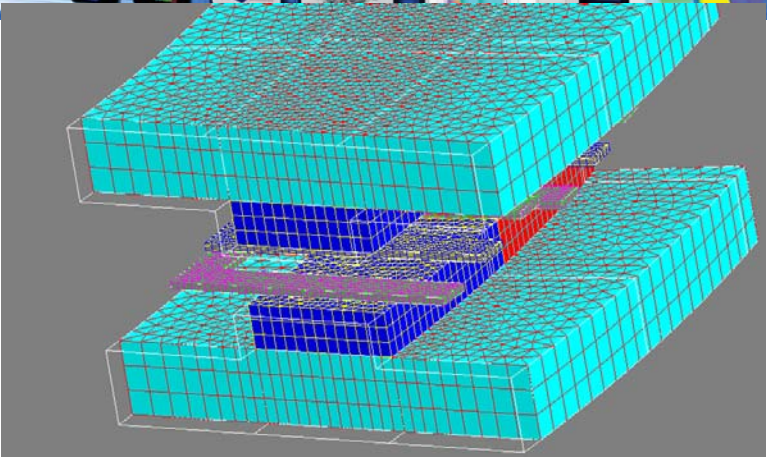
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Mesh


47,000 nodes
145,000 1st order elements



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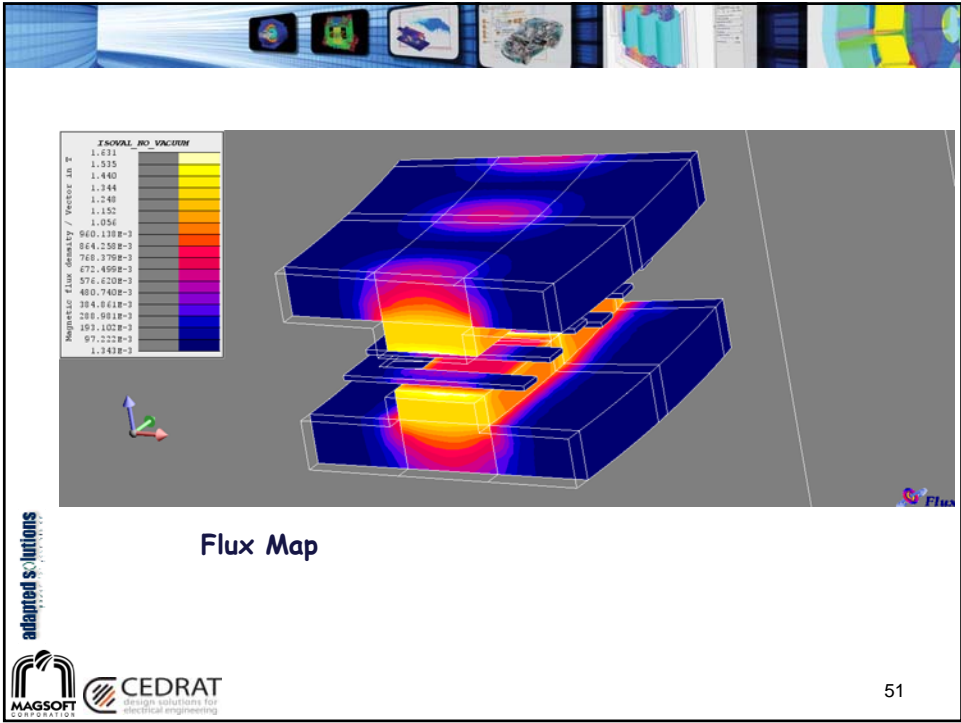
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Eddy currents from motion only

The coils are set in open circuit
the currents must close back inside the coils,
total current across any coil section is none.

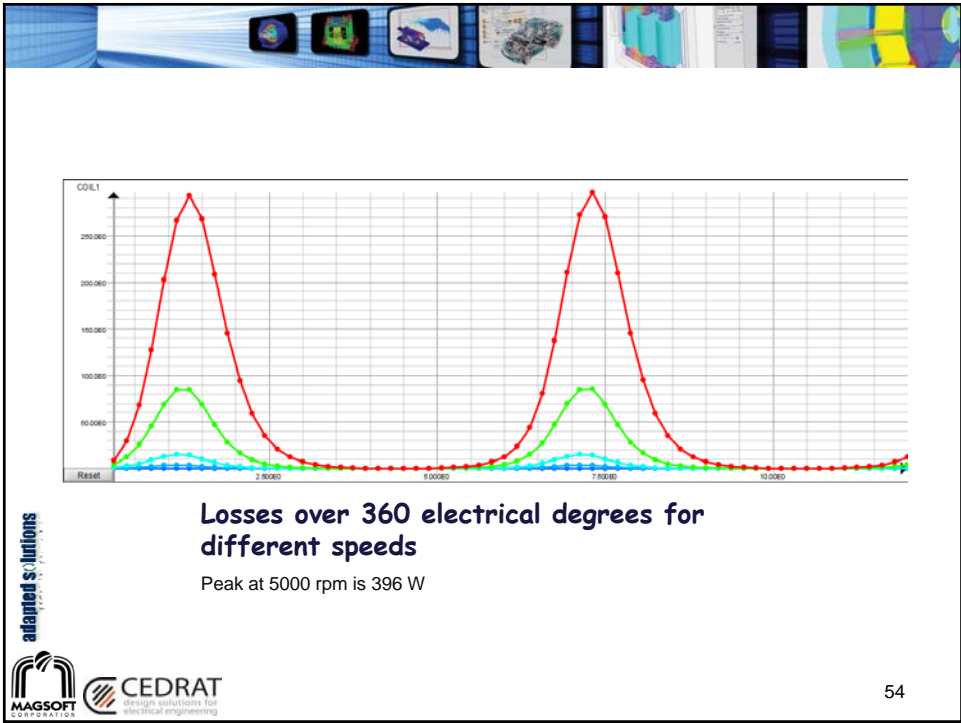
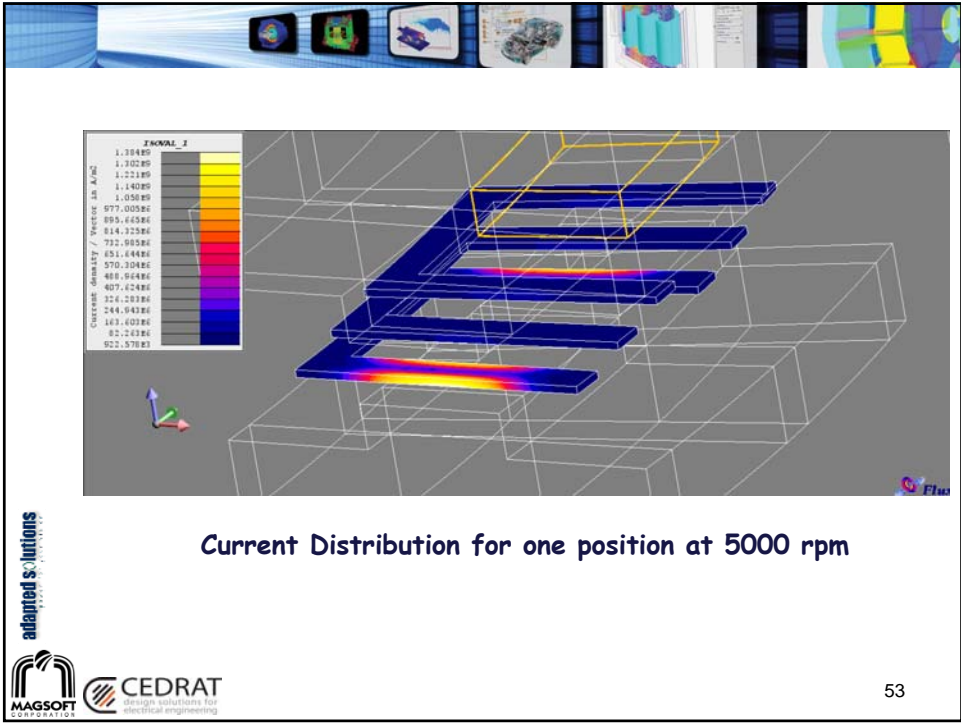
The rotor is set in motion

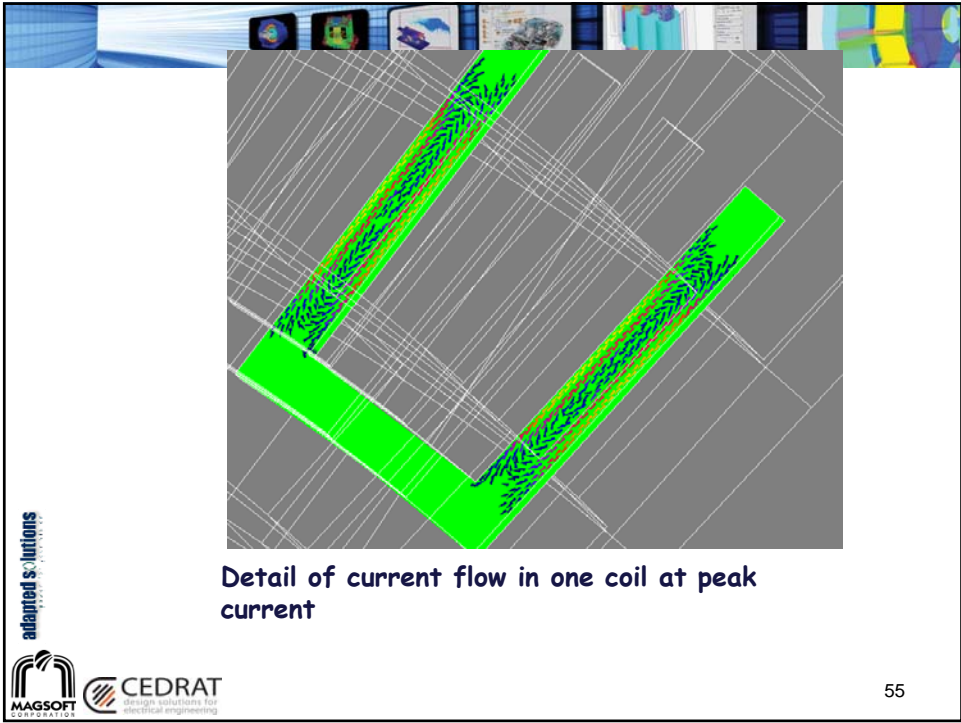
5 speeds:

- 500
- 1000
- 2500
- 5000
- 7500

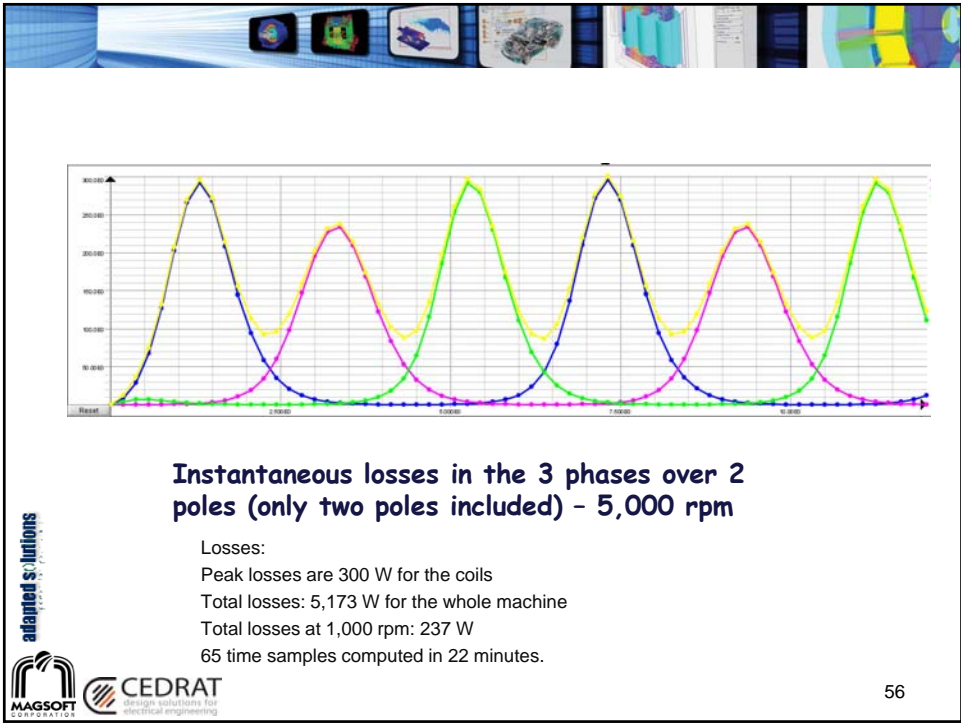
The figure also includes the "adapted solutions" and "MAGSOFT CORPORATION" logos on the left and the "CEDRAT" logo at the bottom center.

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Conclusion

- Eddy currents don't have to remain a mystery
- Computers are going faster
- Codes are able to take advantage of multicore
- Computation where performed on Flux Version 10.4
- Flux connects to Matlab Simulink and Portunus
- Flux is a component of Isight (SIMULIA)
- GOT-It completes Flux with an integrated optimizer.

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